### Time Series Analysis

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#### Class 11

### Forecasting with ARMA

- After the model is chosen and diagnostic is done, the ARMA(p, q) can be used to forecast future values of the time series.
- In probabilistic terms, the forecast is considered on the basis of the collected information on the process at time t, denoted  $\mathcal{F}_t$ , where

$$\mathcal{F}_t = \{X_t, X_{t-1}, X_{t-2}, \cdots, X_0, X_{-1}, \cdots\}.$$

- Goal: To forecast the value of the process at time t + k,  $X_{t+k}$ , conditioning on  $\mathcal{F}_t$ .
- Define  $\hat{X}_{t+k}$  the predictor of  $X_{t+k}$  and  $\hat{x}_{t+k}$  its realization.
- Choose  $\hat{X}_{t+k}$  such that it minimizes the forecast men squared error

$$\mathbb{E}(e_{t+k}^2) = \mathbb{E}(X_{t+k} - \hat{X}_{t+k})^2,$$

where  $e_{t+k} = X_{t+k} - \hat{X}_{t+k}$  is the forecast error and is a measure of the model predictive ability.

• It can be shown that the best predictor  $\hat{X}_{t+k}$  is given by its conditional expected value:

$$\hat{X}_{t+k} = \mathbb{E}(X_{t+k}|\mathcal{F}_t) = \mathbb{E}_t(X_{t+k}).$$

• Consider that for conditional expected values we have

$$\begin{split} \mathbb{E}(X_{t+j}|\mathcal{F}_t) &= x_{t+j} \quad \text{if } j \leq 0\\ \mathbb{E}(X_{t+j}|\mathcal{F}_t) &= \hat{x}_{t+j} \quad \text{if } j > 0 \end{split}$$

• Setting  $e_t = X_t - \hat{X}_t$ ,

$$\begin{split} \mathbb{E}(\epsilon_{t+j}|\mathcal{F}_t) &= e_{t+j} \quad \text{if } j \leq 0 \\ \mathbb{E}(\epsilon_{t+j}|\mathcal{F}_t) &= 0 \quad \text{if } j > 0 \end{split}$$

• Recall that  $e_{t+k}$  is a random variable thus, it is worth to evaluate its probabilistic structure.

- For the ARMA process it can be shown that as the forecasting horizon increases (k→∞):
- the forecast tends to the unconditional mean of the process

$$\lim_{k\to\infty}\hat{X}_{t+j}=\mathbb{E}(X_{t+j}),$$

• the variance of the error tends to the unconditional variance of the process

$$\lim_{k\to\infty} Var(e_{t+j}) = Var(X_t).$$

• Consider a stationary AR(1) process

$$X_t = \delta + \varphi X_{t-1} + \epsilon_t.$$

• If the parameters were known, the one step ahead (k = 1) forecast would be

$$\hat{x}_{t+1} = \mathbb{E}_t(X_{t+1}) = \mathbb{E}_t(\delta + \varphi X_t + \epsilon_{t+1}) = \delta + \varphi x_t.$$

• The forecasting error

$$e_{t+1} = X_{t+1} - \hat{X}_{t+1} = \delta + \varphi x_t + \epsilon_{t+1} - (\delta + \varphi x_t) = \epsilon_{t+1}$$
$$\Rightarrow Var(e_{t+1}) = Var(\epsilon_{t+1}) = \sigma^2.$$

• In order to forecast k = 2 steps ahead:

$$\hat{x}_{t+2} = \mathbb{E}_t(X_{t+2}) = \mathbb{E}_t(\delta + \varphi X_{t+1} + \epsilon_{t+2}) = \delta + \mathbb{E}_t(\varphi X_{t+1})$$
$$= \delta + \varphi \hat{x}_{t+1} = \delta + \varphi (\delta + \varphi x_t) = \delta + \delta \varphi + \varphi^2 x_t = \delta (1 + \varphi) + \varphi^2 x_t.$$

• The forecasting error becomes

$$e_{t+2} = X_{t+2} - \hat{X}_{t+2} = \delta + \varphi X_{t+1} + \epsilon_{t+2} - \delta - \varphi \hat{X}_{t+1}$$
$$= \epsilon_{t+2} + \varphi (X_{t+1} - \hat{X}_{t+1}) = \epsilon_{t+2} + \varphi e_{t+1} = \epsilon_{t+2} + \varphi \epsilon_{t+1}.$$

• Therefore,

$$Var(e_{t+2}) = Var(\epsilon_{t+2} + \varphi \epsilon_{t+1}) = \sigma^2(1 + \varphi^2).$$

• By iterating the procedure, the general k-th steps ahead forecst will be

$$\hat{x}_{t+k} = \delta(1 + \varphi + \varphi^2 + \dots + \varphi^{k-1}) + \varphi^k x_t$$
$$Var(e_{t+k}) = \sigma^2(1 + \varphi^2 + \varphi^4 + \dots + \varphi^{2(k-1)}).$$

• As the horizon increases:

$$\lim_{k\to\infty}\varphi^k=0$$

$$\lim_{k \to \infty} (1 + \varphi + \varphi^2 + \dots + \varphi^{k-1}) = \frac{1}{1 - \varphi}$$
$$\lim_{k \to \infty} (1 + \varphi^2 + \dots + \varphi^{2(k-1)}) = \frac{1}{1 - \varphi^2}$$
$$\lim_{k \to \infty} \hat{x}_{t+k} = \frac{\delta}{(1 - \varphi)}.$$

- That is, for the AR(1), the point forecast converges to the unconditional mean. If δ = 0, then the forecast converges to zero.
- The variance tends to the unconditional variance of the process

$$\lim_{k\to\infty} Var(e_{t+k}) = \frac{\sigma^2}{1-\varphi^2}$$

- The parameters in the model are replaced by their estimates  $\hat{\delta}, \hat{\varphi}, \hat{\sigma^2}.$
- Same conditions hold for the *AR*(*p*). (As *k* increases, the estimate becomes the unconditional mean of the process and the variance becomes the unconditional variance of the process.)

# MA(1)

• Consider the *MA*(1) process

$$X_t = \delta + \theta \epsilon_{t-1} + \epsilon_t.$$

• The one-step ahead forecast is given by

$$\hat{\mathbf{x}}_{t+1} = \mathbb{E}_t(\mathbf{X}_{t+1}) = \mathbb{E}_t(\delta + \theta \epsilon_t + \epsilon_{t+1}) =$$
  
=  $\delta + \theta \mathbb{E}_t(\epsilon_t) + \mathbb{E}_t(\epsilon_{t+1}) = \delta + \theta \mathbf{e}_t.$ 

• Assuming  $\epsilon_t = e_t$ , the one-step ahead forecast error is

$$e_{t+1} = X_{t+1} - \hat{X}_{t+1} = \delta + \theta \epsilon_t + \epsilon_{t+1} - (\delta + \theta e_t) = \epsilon_{t+1}.$$

The expectation is null and the variance

$$Var(e_{t+1}) = Var(\epsilon_{t+1}) = \sigma^2.$$

• The two steps ahead forecast becomes

$$\hat{x}_{t+2} = \mathbb{E}_t(X_{t+2}) = \mathbb{E}_t(\delta + \theta \epsilon_{t+1} + \epsilon_{t+2}) =$$
$$= \delta + \theta \mathbb{E}_t(\epsilon_{t+1}) + \mathbb{E}_t(\epsilon_{t+2}) = \delta.$$

- The forecast with an MA(1) remains constant and equal to the unconditional expectation of  $X_t$  after two steps ahead.
- The same holds for an MA(q).
- In general: not trivial forecasts are obtained only for k ≤ q. For horizon k > q the forecast coincides with the unconditional mean of the model.

The forecasting error is

$$e_{t+2} = X_{t+2} - \hat{X}_{t+2} = \delta + \theta \epsilon_{t+1} + \epsilon_{t+2} - \delta = \theta \epsilon_{t+1} + \epsilon_{t+2}$$

It follows that

$$Var(e_{t+2}) = Var(\theta \epsilon_{t+1} + \epsilon_{t+2}) = \sigma^2(1 + \theta^2)$$

- for any step ahead with k > 2, the variance of the error becomes  $\sigma^2(1 + \theta^2)$ , that is the unconditional variance of the MA(1) process.
- The same can be generalized for an MA(q) process with variance  $\sigma^2(1 + \theta_1^2 + \cdots + \theta_q^2)$ .

## Forecast with ARMA(1,1)

• Consider the ARMA(1,1)

$$X_t = \delta + \varphi X_{t-1} + \theta \epsilon_{t-1} + \epsilon_t.$$

• The uno step ahead forecast is given by

$$\hat{x}_{t+1} = \mathbb{E}_t(X_{t+1}) = \mathbb{E}_t(\delta + \varphi X_t + \theta \epsilon_t + \epsilon_{t+1}) = \delta + \varphi x_t + \theta e_t.$$

• The forecast error is

$$e_{t+1} = X_{t+1} - \hat{X}_{t+1} = \epsilon_{t+1}.$$

Its variance is

$$Var(e_{t+1}) = \sigma^2.$$

• The forecast for k = 2 is

$$\begin{aligned} \hat{x}_{t+2} &= \mathbb{E}_t(X_{t+2}) = \mathbb{E}_t(\delta + \varphi X_{t+1} + \theta \epsilon_{t+1} + \epsilon_{t+2}) = \delta + \varphi \hat{x}_{t+1} = \\ &= \delta(1 + \varphi) + \varphi^2 x_t + \theta \varphi e_t. \end{aligned}$$

• The forecast error is

$$e_{t+2} = X_{t+2} - \hat{X}_{t+2} = \delta + \varphi X_{t+1} + \theta \epsilon_{t+1} + \epsilon_{t+2} - (\delta + \varphi \hat{X}_{t+1}) =$$
$$= \varphi e_{t+1} + \theta \epsilon_{t+1} + \epsilon_{t+2} = (\varphi + \delta) \epsilon_{t+1} + \epsilon_{t+2}.$$

• Notice that it has null expected value and variance equal to

$$Var(e_{t+2}) = \sigma^2((\varphi + \delta)^2 + 1).$$

• By iterating, the k steps ahead forecast is given by

$$\hat{x}_{t+k} = \delta(1 + \varphi + \varphi^2 + \dots + \varphi^{k-1}) + \varphi^k x_t + \theta \varphi^{k-1} e_t.$$

- As k goes to ∞ the variance tends to the unconditional variance of the process.
- Notice that after the second step ahead the predictor resembles that of an AR(1). Indeed, its asymptotic behaviour is exactly that of an AR(1).
- When k > 1 the behaviour of the forecast is dominated by the autoregressive part.

- For a general *ARMA*(*p*, *q*) similar results to those seen for the *ARMA*(1,1) can be obtained.
- When k > q the autoregressive part drives the forecast that converges to the unconditional mean of the ARMA(p, q) as k tends to ∞.
- Similarly, the variance of the forecast error converges to the unconditional variance.